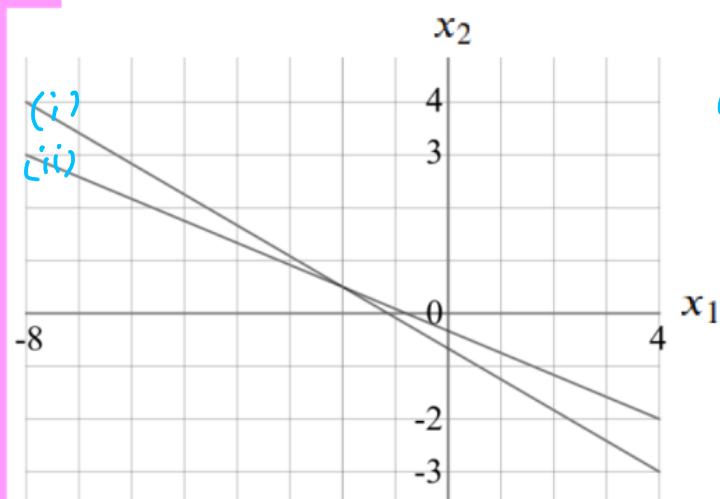


1 The equations of the two lines in the sketch below are



$$(i) \quad x_2 = 4 - \frac{7}{12}(x_1 + 8)$$

$$(ii) \quad x_2 = 3 - \frac{5}{12}(x_1 + 8)$$

(a) Write this system in matrix vector form $Ax = b$.

(b) Compute $\|A\|_\infty$ and $\|A^{-1}\|_\infty$

(c) Compute the infinity-norm condition number of matrix A. Based on this number, is the linear system well conditioned or not? Explain.

(d) Citing an appropriate theorem, compute a bound on the norm of the change in the solution if δA is zero and $\|\delta b\|/\|b\| \leq 0.01$.

(a)

$$\begin{bmatrix} \frac{7}{12} & 1 \\ \frac{5}{12} & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 4 - \frac{56}{12} \\ 3 - \frac{40}{12} \end{bmatrix}$$

(b) $\|A\|_\infty = \max_i \sum_j |a_{ij}| = \frac{7}{12} + 1 = \frac{19}{12}$

$$A^{-1} = \frac{1}{\frac{7}{12} - \frac{5}{12}} \begin{bmatrix} 1 & -1 \\ -\frac{5}{12} & \frac{7}{12} \end{bmatrix} = \frac{12}{2} \begin{bmatrix} 1 & -1 \\ -\frac{5}{12} & \frac{7}{12} \end{bmatrix} = \begin{bmatrix} 6 & -6 \\ -5 & 7 \end{bmatrix}. \text{ So } \|A^{-1}\|_\infty = 6 + 6 = 12$$

(c) $\kappa_\infty(A) = \|A\|_\infty \|A^{-1}\|_\infty = \frac{19}{12} \cdot 12 = 19.$

Roughly speaking errors or changes in the data A, b will be amplified by as much as a factor of 19.

This is not ideal (the ideal is no amplification at all: $\kappa=1$) but not terrible. (See part (d).)

(d) We have Thm 3.10: $\frac{\| \delta x \|}{\| x \|} \leq \frac{\kappa(A)}{(1 - \| SA \| \| A^{-1} \|)} \left(\frac{\| \delta b \|}{\| b \|} + \frac{\| SA \|}{\| A \|} \right)$

If $SA = 0$, $\frac{\| \delta x \|}{\| x \|} \leq \frac{\kappa(A) \| \delta b \|}{\| b \|}$

If $\kappa(A) = 19$ and $\frac{\| \delta b \|}{\| b \|} \leq 0.01$, then $\frac{\| \delta x \|}{\| x \|} \leq 19 \cdot 0.01 = .19$

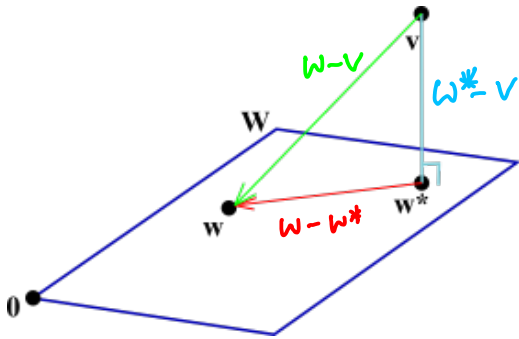
Thus a 1% change in b can yield no more than a 19% change in x .

2 Let V be a vector space with an inner product $(\cdot, \cdot) \rightarrow \mathbb{R}^+$, and let $\|\cdot\|$ be the norm induced by this inner product. That is, $\|v\|^2 = (v, v)$.

Let W be a subspace of V , and let $v \in V$, $w^* \in W$ be such that, with respect to the inner product above, $w^* - v$ is orthogonal to every $w \in W$.

Show that no vector $w \in W$ is closer to v than w^* is.

That is, show that $\|v - w\| \geq \|v - w^*\| \forall w \in W$.



Want to show that

$$\|w - v\| \geq \|w^* - v\| \quad \forall w \in W.$$

$$w - v = w^* - v + w - w^*$$

So

$$\|w - v\|^2 = (w - v, w - v)$$

$$= (w^* - v + w - w^*, w^* - v + w - w^*)$$

$$= (w^* - v, w^* - v) + (w^* - v, w - w^*) + (w - w^*, w^* - v) + (w - w^*, w - w^*)$$

because $w - w^* \in W$ and $w^* - v \in W^\perp$ by hypothesis

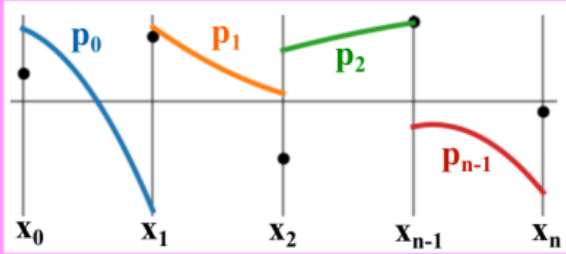
$$= \|w^* - v\|^2 + \|w - w^*\|^2$$

$$\geq \|w^* - v\|^2 \quad \text{because this term is non-negative.} \quad \text{QED.}$$

Recall that the cubic spline interpolant is a piecewise cubic function whose value and first and second derivatives are continuous at the nodes (and everywhere else). With n subintervals, these requirements impose $4n - 2$ constraints on the $4n$ parameters of the n cubic pieces, which are supplemented by 2 additional constraints, such as the "natural" or "clamped" end conditions.

(a) If we chose instead to build a piecewise-**quadratic** interpolant to data $\{(x_j, y_j)\}_{j=0,1,\dots,n}$ with nodes $a = x_0 < x_1 < \dots < x_{n-1} < x_n = b$, write down an appropriate set of constraints, and compare the total number of constraints with the number of parameters.

(b) Can you suggest a sensible way of supplementing the constraints to complete the specification of the interpolant? If so, do so. If not, say why not.



(a) We have n quadratic pieces $p_i(x) = a_i + b_i x + c_i x^2$, $i=1, \dots, n$.
That's a total of $3n$ parameters (degrees of freedom).

For interpolation, we need

$$\left. \begin{array}{l} p_i(x_i) = y_i, \quad i=0, \dots, n-1 \rightarrow n \text{ constraints} \\ p_i(x_{i+1}) = y_{i+1}, \quad i=0, \dots, n-1 \rightarrow n \text{ constraints} \end{array} \right\} 2n \text{ constraints so far}$$

We can accommodate n more constraints.

We could make the interpolant C^1 by requiring derivative matching at the interior nodes:

$$p'_{i-1}(x_i) = p'_i(x_i), \quad i=1, \dots, n-1 \rightarrow n-1 \text{ constraints.}$$

We now have $3n-1$ equations in $3n$ variables:
we need 1 more equation!

(b) Can't impose any condition at both ends.

I don't have any bright ideas off the top of my head for a natural additional condition. Maybe that's why we don't hear about quadratic splines?

Devise a Householder reflector (an orthogonal matrix) H_1 which will zero-out the subdiagonal portion of the first column of the matrix A below. State the projector P that you use in constructing H_1 , and give the product $H_1 A$.

$$\begin{bmatrix} 3 & 5 \\ 0 & 1 \\ 4 & 7 \end{bmatrix}$$

No part of the calculation generates numbers with more than one digit after the decimal point.

$$z = \begin{bmatrix} 3 \\ 0 \\ 4 \end{bmatrix}, \quad \|z\|_2 = \sqrt{3^2 + 4^2} = 5, \quad w = \begin{bmatrix} 5 \\ 0 \\ 0 \end{bmatrix} \text{ (or its negative)}$$

$$v \equiv w - z = \begin{bmatrix} 5 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 3 \\ 0 \\ 4 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ -4 \end{bmatrix}.$$

$$v^T v = (2)^2 + (-4)^2 = 20, \quad v v^T = \begin{bmatrix} 2 \\ 0 \\ -4 \end{bmatrix} \begin{bmatrix} 2 & 0 & -4 \end{bmatrix} = \begin{bmatrix} 4 & 0 & -8 \\ 0 & 0 & 0 \\ -8 & 0 & 16 \end{bmatrix}$$

$$P = \frac{v v^T}{v^T v} = \begin{bmatrix} .2 & 0 & -.4 \\ 0 & 0 & 0 \\ -.4 & 0 & .8 \end{bmatrix}$$

$$H_1 = I - 2P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} .4 & 0 & -.8 \\ 0 & 0 & 0 \\ -.8 & 0 & 1.6 \end{bmatrix} = \begin{bmatrix} .6 & 0 & .8 \\ 0 & 1 & 0 \\ .8 & 0 & -.6 \end{bmatrix}$$

$$H_1 A = \begin{bmatrix} .6 & 0 & .8 \\ 0 & 1 & 0 \\ .8 & 0 & -.6 \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 0 & 1 \\ 4 & 7 \end{bmatrix} = \begin{bmatrix} 5 & 3.0 + 5.6 \\ 0 & 1 \\ 0 & 4.0 - 4.2 \end{bmatrix} = \begin{bmatrix} 5 & 8.6 \\ 0 & 1 \\ 0 & -0.2 \end{bmatrix}$$

↑
no calculation
required

With respect to the inner product $(f, g) = \int_0^1 f(x)g(x)dx$, find the least squares approximation to $f(x) = e^x$ on $[0, 1]$ within the subspace of $C[0, 1]$ spanned by the functions $\{1, x\}$.

Our approximation is of the form $p(x) = c_0 \cdot 1 + c_1 \cdot x$.

We require the error $p-f$ to be orthogonal to each of the basis functions.

Thus (i) $\int_0^1 (c_0 + c_1 x - e^x) \cdot 1 dx = 0$

and (ii) $\int_0^1 (c_0 + c_1 x - e^x) x dx = 0$

(i) $\left| c_0 x + c_1 \frac{x^2}{2} - e^x \right|_0^1 = 0$

$(c_0 + \frac{c_1}{2} - e) - (0 + 0 - 1) = 0 \rightarrow \boxed{c_0 + \frac{c_1}{2} = e - 1}$

(ii) $\int_0^1 x e^x dx \stackrel{\text{by parts}}{=} x e^x \Big|_0^1 - \int_0^1 e^x dx = e - e^x \Big|_0^1 = e - (e - 1) = 1$

So $\left| c_0 \frac{x^2}{2} + c_1 \frac{x^3}{3} \right|_0^1 - 1 = 0 \rightarrow \frac{1}{2}c_0 + \frac{1}{3}c_1 = 1$
 $\boxed{c_0 + \frac{2}{3}c_1 = 2}$

Subtracting (i) from (ii):

$\left(\frac{2}{3} - \frac{1}{2} \right) c_1 = 3 - e \rightarrow c_1 = \frac{18 - 6e}{\frac{1}{6}}$

Then $c_0 = 2 - \frac{2}{3}(18 - 6e) = 2 - (12 - 4e) = -10 + 4e$

And so $\boxed{p(x) = -10 + 4e + (18 - 6e)x}$

