

## Day 16 Approximation with trigonometric functions

1. "Best" approximation of  $f$  in vector space  $V = C[0, 2\pi]$

with inner product  $(f, g) = \int f \bar{g} = \int_0^{2\pi} f(x) \bar{g}(x) dx$

2. Interpolation

1. For  $f$  in  $V$ , approximate it by an element of

$$W_{2k} = \text{span} \{ \omega_{-k}, \dots, \omega_{-1}, \omega_0, \omega_1, \dots, \omega_k \}$$

where ...  $\omega_j(x) = e^{ijx} = (e^{ix})^j$  where  $i = \sqrt{-1}$ ,  $j = -k, \dots, 0, \dots, k$

$\{\omega_j\}$  is a basis for its span because the elements are orthogonal w.r.t. the inner product, hence linearly independent.

Prop:  $(\omega_j, \omega_l) = 2\pi \delta_{jl}$

Proof:  $(\omega_j, \omega_l) = \int_0^{2\pi} e^{ijx} e^{-ilx} dx = \int_0^{2\pi} e^{i(j-l)x} dx$

$$= \begin{cases} \int_0^{2\pi} e^0 dx = \int_0^{2\pi} 1 dx = 2\pi, & j=l \\ \int_0^{2\pi} \cos(j-l)x dx + i \int_0^{2\pi} \sin(j-l)x dx = 0 + 0 = 0 & j \neq l \end{cases} \quad \text{😊}$$

The "best" approximation to  $f$  in the subspace, i.e. the one with the smallest error is one whose error is orthogonal to the subspace.

Proof:  $W \subset V$ ,  $f \in V$ ,  $\omega_0 \in W$ ,  $w \in W$

Set  $r_0 = \omega_0 - f$ ,  $r = w - f$

Let  $r_0$  be orthogonal to all vectors  $w \in W$ . \*

Can write  $r = r_0 + (w - \omega_0)$

$$\|r\|^2 = (r, r)$$

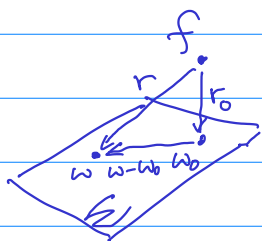
$$= (r_0 + (w - \omega_0), r_0 + (w - \omega_0))$$

$$= (r_0, r_0) + (w - \omega_0, r_0)$$

$$+ (r_0, w - \omega_0) + (w - \omega_0, w - \omega_0)$$

$$= \|r_0\|^2 + \|w - \omega_0\|^2$$

This is minimized if  $w = \omega_0$ .



Best approximation  $g_{2k} \in W_{2k}$  for  $f \in V$   
 is an element of  $W_{2k}$  such that

$$(g_{2k} - f, w_l) = 0 \quad \forall l \in -k, \dots, 0, \dots, k$$

or

$$* (g_{2k}, w_l) = (f, w_l) \quad \forall l.$$

Writing  $g_{2k}(x) = \sum_{j=-k}^k \alpha_j w_j(x)$ , we can readily find the  $\{\alpha_j\}$  *plug into \**

$$\left( \sum_j \alpha_j w_j, w_l \right) \stackrel{\text{want}}{=} \left( f, w_l \right)$$

$$= \sum_j \alpha_j (w_j, w_l) = \alpha_j 2\pi \delta_{jl} = \underline{2\pi \alpha_j}$$

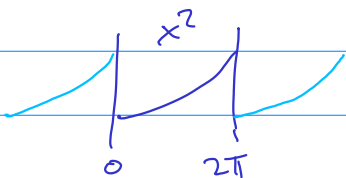
$$\rightarrow \boxed{\alpha_l = \frac{1}{2\pi} (f, w_l)} *$$

With this formula for the  $\{\alpha_j\}$ , we define

Def 4.18  $g_{\infty}(x) = \sum_{j=-\infty}^{\infty} \alpha_j e^{ijx}$

and call it the complex Fourier series of  $f$ ,

Examples:



periodic extension  
 of  $x^2$  to  $\mathbb{R}$   
 is not continuous.

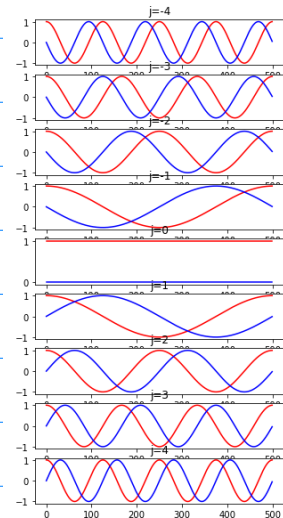
If periodic extension of  $f$  is continuous  
 and even better, smooth, then we expect  
 better results.

## 4.5.1 Least squares trigonometric approximation

### A subspace of $C[0,2\pi]$ spanned by complex exponentials

```
%matplotlib inline
from nsm import *
plt.figure(figsize=(5,10))
k = 4
x = np.linspace(0,2*np.pi,500,endpoint=False)
w = np.exp(1j*x)
for j in range(-k,k+1):
    plt.subplot(2*k+1,1,j+k+1)
    plt.plot(np.real(w**j),'r')
    plt.plot(np.imag(w**j),'b')
    plt.title(f'j={j}')
# real part shown in red
# imag part shown in blue
```

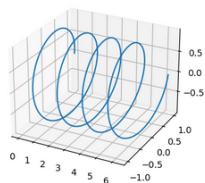
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```



```
%matplotlib notebook
ax = plt.figure().add_subplot(projection='3d')
k = 4
x = np.linspace(0,2*np.pi,500,endpoint=False)
w = np.exp(1j*x)
for j in [k]:
    plt.plot(x,np.real(w**j),np.imag(w**j));
```

<IPython.core.display.Javascript object>

Plotted in  $Cx[0,2\pi]$



These are the functions we are building our approximation with.

```
import matplotlib.pyplot as plt
import numpy as np
from scipy.integrate import quadrature
```

```
%matplotlib inline
twopi = 2*np.pi
i = 1j
def f1(x): return np.exp(np.cos(x)+np.sin(x)/2) # a smooth periodic function that is not a combination of trig funct
def f2(x): return x**2 # a function with discontinuous periodic extension
def f3(x): return x*(twopi-x) # a function with continuous periodic extension but jump in derivative
def f4(x): x1 = (x-np.pi)/np.pi; return x1**4 - 2*x1**2

f = f2

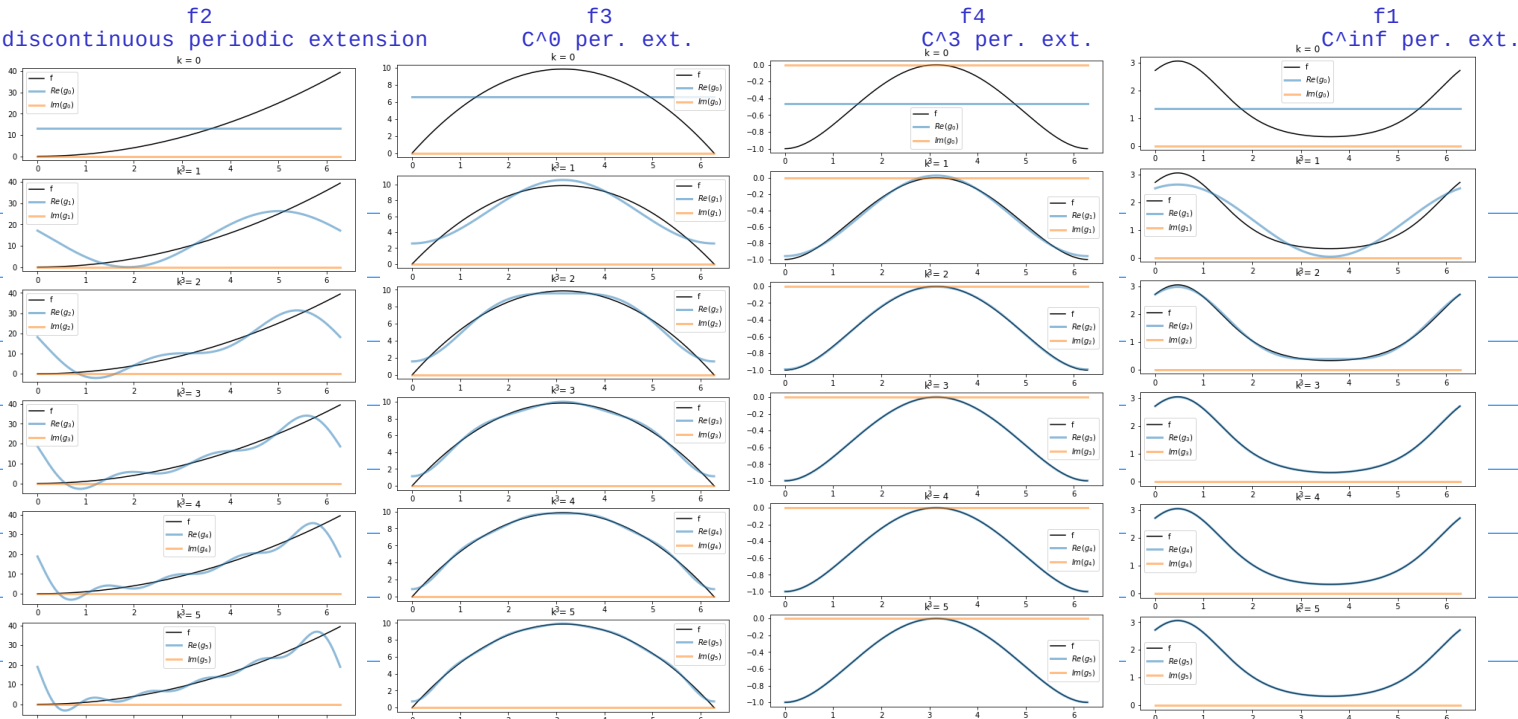
x = np.linspace(0,twopi,1000)
kstop = 6
plt.figure(figsize=(8,16))
for k in range(kstop):
    plt.subplot(kstop,1,k+1)
    plt.plot(x,f(x),'k',label='f');
    gk = np.zeros_like(x,dtype=complex)
    alpha = []
    for j in range(-k,k+1):
        wj = np.exp(i*j*x)
        def integrand(x): return f(x)*np.exp(-i*j*x)
        twopiaj,err = quadrature(integrand,0,twopi) # gaussian quadrature f = f2
        alphaj = twopiaj/twopi
        alpha.append(alphaj)
        gk += alphaj*wj
    plt.plot(x,np.real(gk),label=f'$Re(g_{k})$',lw=3,alpha=0.5)
    plt.plot(x,np.imag(gk),label=f'$Im(g_{k})$',lw=3,alpha=0.5)
    plt.title(f'k = {k}')
    #print(np.round(a,4))
    plt.legend()
```

```
import matplotlib.pyplot as plt
import numpy as np
from scipy.integrate import quadrature
```

```
%matplotlib inline
twopi = 2*np.pi
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    for j in range(-k,k+1):
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        gk += alphaj*wj
    plt.plot(x,np.real(gk),label=f'$Re(g_{k})$',lw=3,alpha=0.5)
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    plt.title(f'k = {k}')
    #print(np.round(a,4))
    plt.legend()
```

Convergence as  $k$  increased in the 4 examples above is illustrated on the next page.



Rate of convergence: infinity norm as a power of  $1/k$  as slope of log-log plot  $f=f1$

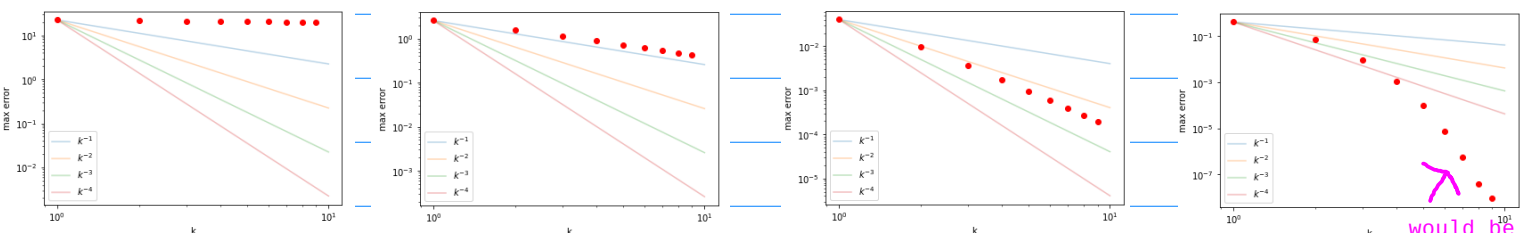
```

x = np.linspace(0, twopi, 1000)
kstop = 10
plt.figure(figsize=(8,16))
kk = np.linspace(1, kstop, 3)
for k in range(1, kstop):
    gk = np.zeros_like(x, dtype=complex)
    alpha = []
    for j in range(-k, k+1):
        wj = np.exp(i*j*x)
        def integrand(x): return f(x)*np.exp(-i*j*x)
        twopiaj, err = quadrature(integrand, 0, twopi) # gaussian quadrature
        alphaj = twopiaj/twopi
        alpha.append(alphaj)
        gk += alphaj*wj

maxerror = np.abs(f(x)-gk).max()
print(k, maxerror)
if k==1:
    for p in range(1,5):
        plt.loglog(kk, kk**(-p)*maxerror, label='$k^{'+str(p)+'}$', alpha=0.3)

plt.loglog(k, maxerror, 'ro')
plt.xlabel('k'); plt.ylabel('max error')
plt.legend();

```



would be steeper here if my quadrature for the alphas were more accurate.

In agreement with empirical observations just made, we have thus

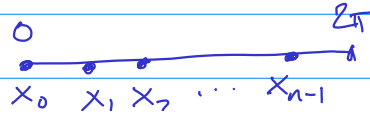
Thm 4.167 (Proof in next Homework)

If  $f$  is continuous on  $[0, 2\pi]$  and  $f^{(p)}(0) = f^{(p)}(2\pi)$  for all  $p=0, 1, \dots, n-1$  then  $\|f - g_{2k}\|_{\infty} = O\left(\frac{1}{k^{n-1}}\right)$ .

And if  $f \in C^{\infty}(\mathbb{R})$  then  $\|f - g_{2k}\|_{\infty} \rightarrow 0$  faster than any power of  $\frac{1}{k}$ . ("spectral" convergence)

## 2. Interpolation with trig polynomials

Define  $x_k = \frac{2\pi k}{n}$ ,  $k=0,1,\dots,n-1$



Thm 4.18 Define  $p(x) = \sum_{j=0}^{n-1} c_j e^{ijx}$ ,  $c_j = \frac{1}{n} \sum_{k=0}^{n-1} f(x_k) e^{-ijx_k}$ ,  $x_k = \frac{2\pi k}{n}$ .

$p(x_v) = f(x_v)$ ,  $v=0,\dots,n-1$ . I.e.  $p$  interpolates the data.

Proof.

$$\begin{aligned}
 p(x_v) &= \sum_{j=0}^{n-1} c_j e^{ijx_v} = \frac{1}{n} \sum_{j=0}^{n-1} \sum_{k=0}^{n-1} f(x_k) e^{-ijx_k} e^{ijx_v} \\
 &= \sum_{k=0}^{n-1} f(x_k) \frac{1}{n} \sum_{j=0}^{n-1} e^{-ijx_k} e^{ijx_v} \quad (\text{re-ordering sums}) \\
 &= \sum_{k=0}^{n-1} f(x_k) \left[ \frac{1}{n} \sum_{j=0}^{n-1} e^{ij(x_v - x_k)} \right] \\
 &= \sum_{k=0}^{n-1} f(x_k) \left[ \frac{1}{n} \sum_{j=0}^{n-1} e^{-ikx_j} e^{ivx_j} \right] \\
 &= \sum_{k=0}^{n-1} f(x_k) \left[ \frac{1}{n} N \delta_{jk} \right] \\
 &= f(x_v). \quad \text{☺}
 \end{aligned}$$

### 4.5.2 Discrete Fourier transform

```

from nsm import * # numpy as np, sympy as sp, matplotlib.pyplot as plt

n = 8
x = np.linspace(0, 2*np.pi, 500, endpoint=False)
w = np.exp(1j*x)
for j in range(n):
    plt.subplot(n, 1, j+1)
    plt.plot(np.real(w**j), 'r')
    plt.plot(np.imag(w**j), 'b')

```

The functions  $\exp(ijx)$  for  $j=0,1,\dots,n-1$

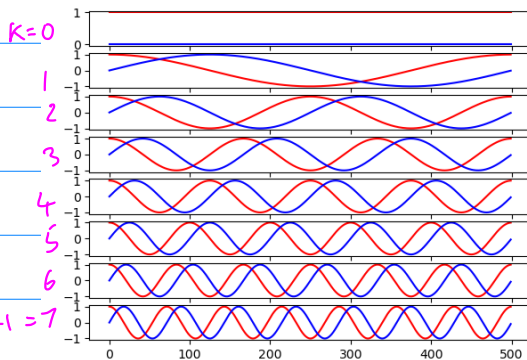
```

y = np.random.randn(n)
x = np.linspace(0, 2*np.pi, n, endpoint=False)
plt.plot(x, y, 'ko', alpha=0.5)
plt.plot(x, y*0, 'ko', alpha=0.25)
nn = 1000
xx = np.linspace(0, 2*np.pi, nn, endpoint=False)
ww = np.exp(1j*xx)
c = A@y
#print(c)
p = np.zeros(nn, dtype=complex)
for j in range(n):
    print(c[j])
    p += c[j]*ww**j
plt.plot(xx, np.real(p), 'r')
plt.plot(xx, np.imag(p), 'b')
plt.axhline(0)
plt.xlim(0, 2*np.pi)

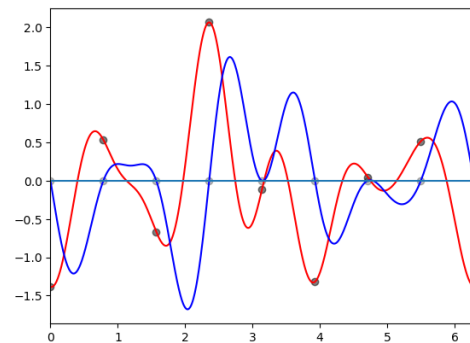
(-0.04019157128643404+0j)
(-0.1328542936776702-0.21156295561908092j)
(-0.1086750278701828+0.42071622935739034j)
(-0.18608452827529598-0.3901145891202525j)
(-0.4890368466098044-2.909595696206072e-16j)
(-0.18608452827529676+0.3901145891202522j)
(-0.1086750278701653-0.4207162293573902j)
(-0.1328542936776707+0.21156295561908128j)

(0.0, 6.283185307179586)

```



red real part  
blue imag part



This is indeed an interpolant, but it leaves a lot to be desired! Unwarranted wiggles, and strange imaginary part for data that is real.

We will construct a better one next class (Day 17).